

Cyclotron option for Accelerator Driven System



Seunghwan Shin, Garam Hahn, T.-Y. Lee, Taekyun Ha and Jinyul Hu

Pohang Accelerator Laboratory

Jeonghwan Park and Seungyong Hahn

Seoul National University

Hyunwook Kim

National Fusion Research Institute

Moses Chung

UNIST

June 30, 2020



Content

❖ Introduction

- Motivation
- Requirement
- Two options for ADS

❖ Current activities on cyclotron option for ADS

- Research exchange association for cyclotron
- Beam dynamic program development
- Preliminary study with HTC superconducting magnet

❖ Future plan

- 0.3 MW cyclotron system: Therapy cyclotron as the first step toward ADS
- 3 MW cyclotron system: Main cyclotron for ADS

Nuclear power

❖ The long-term threats facing humanity

- Climate change
- Exhaustion of energy

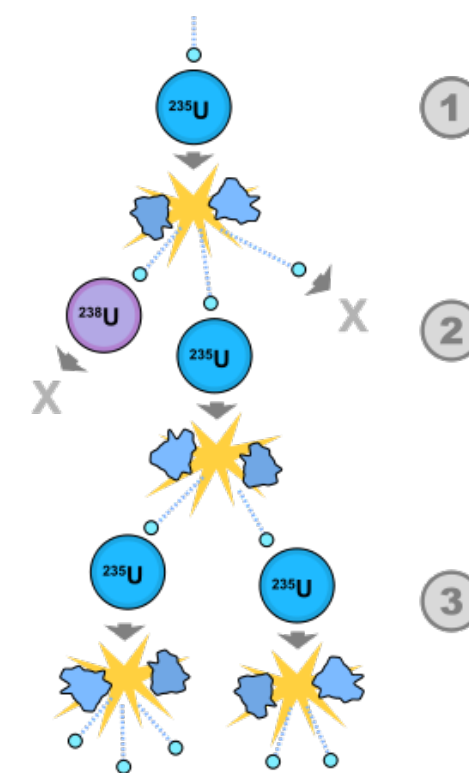
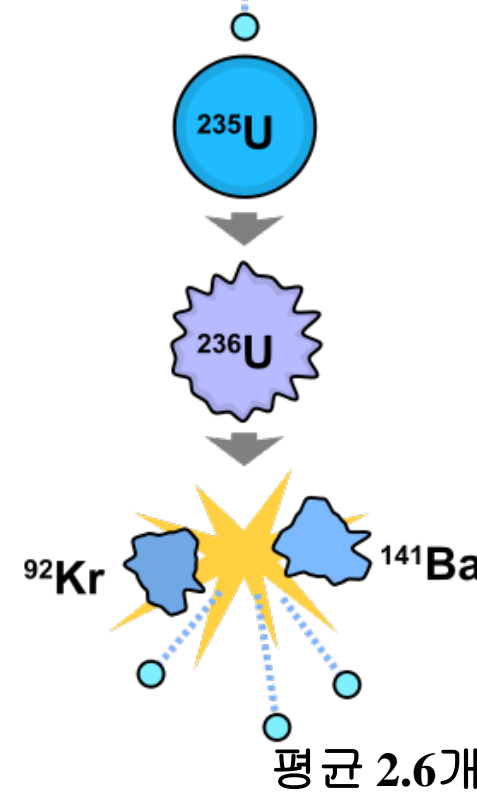
❖ Nuclear power

- The practicable alternative
- Strong advantage and strong drawback

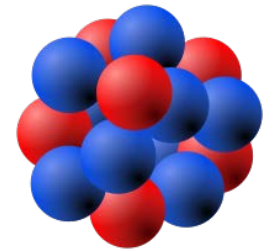
❖ Nuclear power drawback

- Chernobyl disaster (Supercritical)
- Radiation active waste

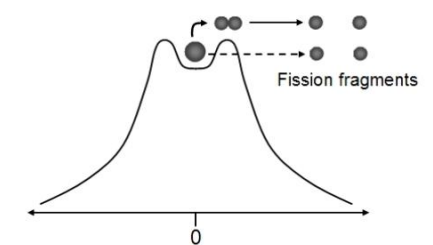
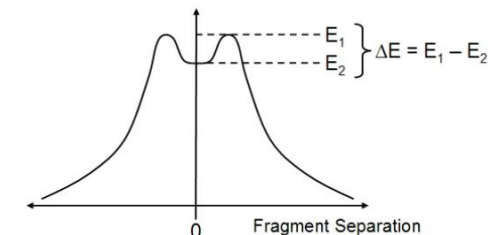
- 원료=우라늄 238(96%)+우라늄 235(4%)
(자연상태 우라늄: U238(99.3%))



Chain Reaction



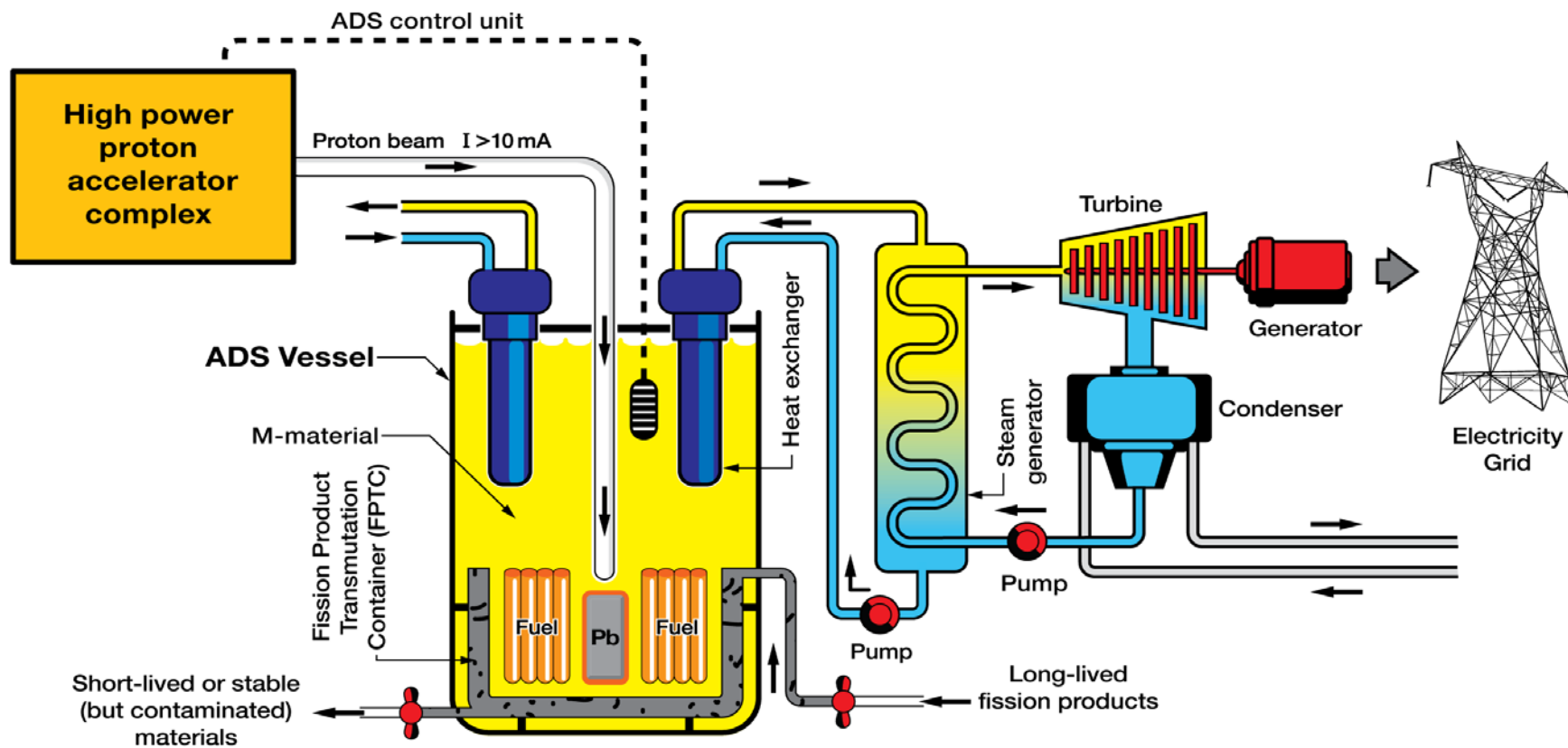
핵=양성자(red)+중성자(blue)
중성자는 핵반응의 필수요소



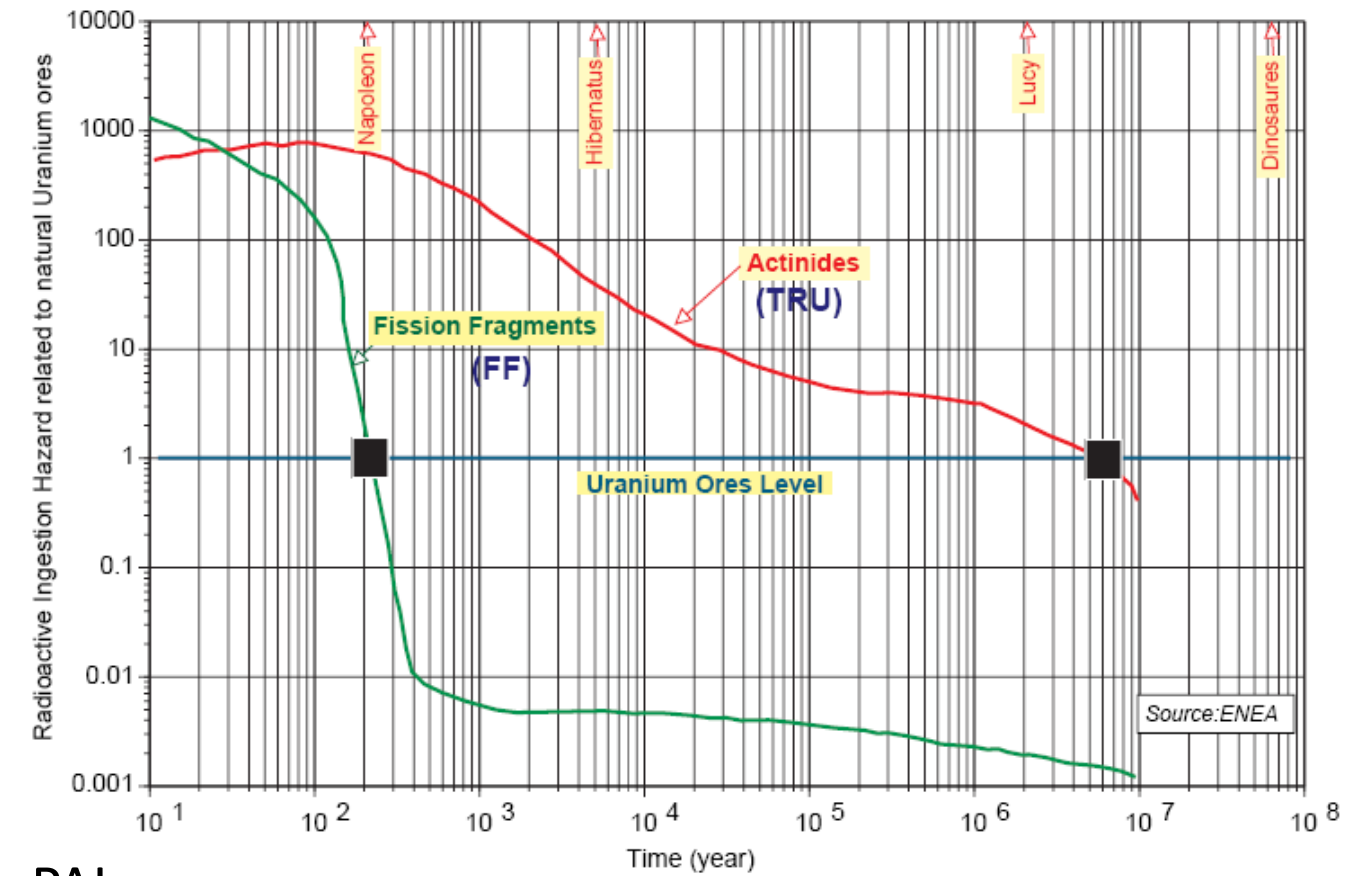
The Nuclear Potential and Nuclear Fission

T.-Y. Lee, ADS meeting, PAL

Accelerator Driven System (ADS)



T.-Y. Lee, ADS meeting, PAL



Source: ENEA

Requirement for ADS

Resulting beam requirements

- Particle type: protons
- Particle energy: > 500 MeV
- Beam power: multiple MW
 - depending on chosen sub-criticality, reactor design,...
- Very high reliability
 - Beam trips must be resolved within a few seconds
 - Imposing severe thermal stress on the reactor materials/components
 - Any longer beam trip requires a time-consuming restart of the reactor.
 - Consequence: MTBF $>$ multiple weeks

Requirement for ADS

Derived accelerator requirements

- DC-operation
 - less space charge, reduced stress on spallation target, solid state amplifiers possible, ...
- Fault tolerance schemes needed: Within a few seconds:
 - Detect failure
 - Deploy a new configuration
 - Fast recommissioning: return to full-power beam-operation
- 2 accelerator options:
 - Cyclotron
 - Linac
 - N.B.: also a 400 MeV FFAG options studied

Two options for ADS

- ❖ Our working group has been performing two options: Cyclotron (this presentation) and Linac (Prof. Chung).
- ❖ Each option has their own advantage and disadvantage.

[Cyclotron]

Simple

Cost-effective

Limit to get energy

NC or SC

Good reliability

PSI / Texas A&M

...



[Linac]

Large scale

Expensive

Easy to get energy

SC

Depend on SRF

C-ADS / MYRRHA

...

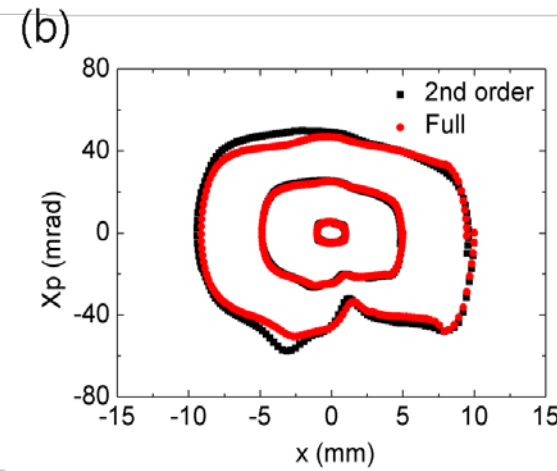
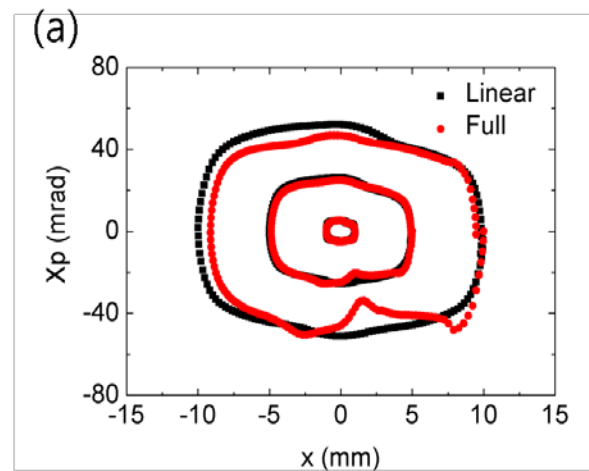
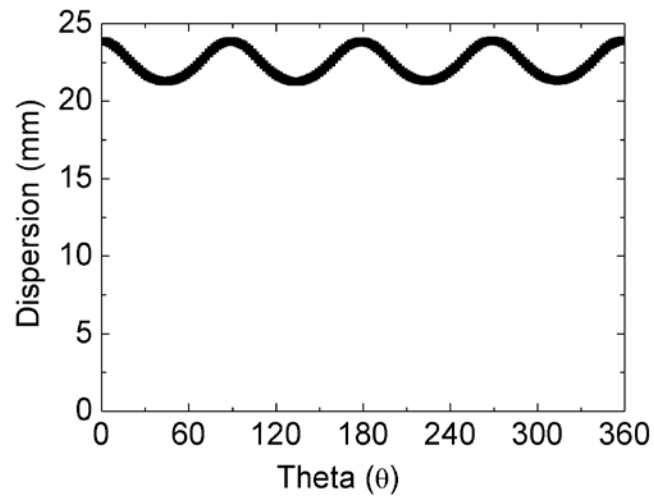
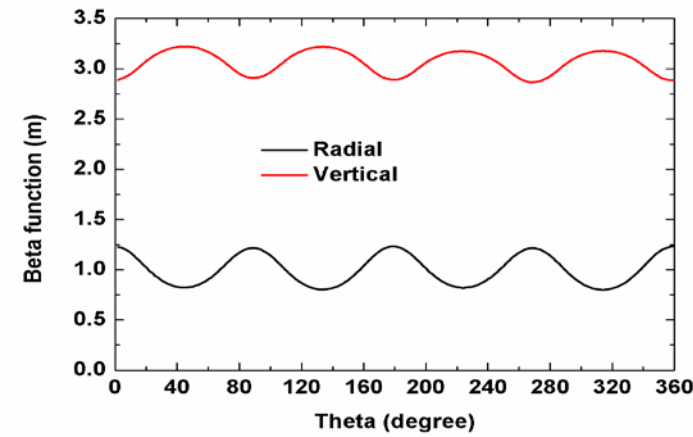
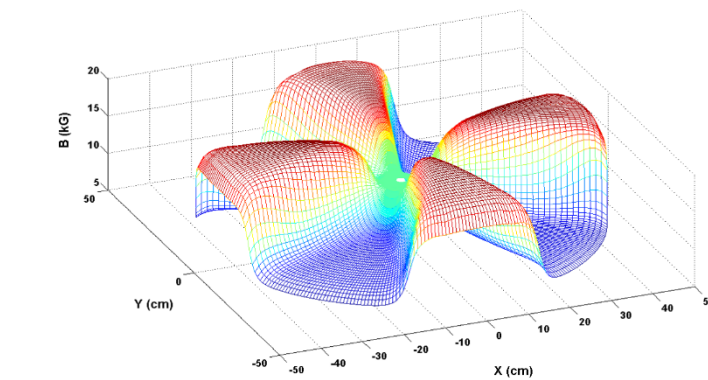
Working group in Korea

- ❖ No budget but working group on study stage.
- ❖ PAL: Design, Beam dynamics, RF, Vacuum, etc.
 - S. Shin, G. Hahn, J. Hu, B. Oh, T. Ha
- ❖ SNU: HTC SC magnet
 - S. Hahn, J. Park
- ❖ KERI: SC magnet
 - J. Cho,
- ❖ KBSI: Ion source
 - B. Lee, J. Park
- ❖ JINR, NFRI, UNIST: Review and magnet design
 - H. Kim, M. Chung
- ❖ Research exchange association for cyclotron: SKKU, IBS, KBSI, KAERI, SNU, KU, KERI, PAL, UNIST



Beam dynamics program I

- ❖ Equilibrium orbit program with second order transfer matrix.
- ❖ This program might be necessary on high vertical focusing field for ADS.
- ❖ Collaboration result between PAL and UNIST



$$\begin{aligned}\frac{dx}{d\theta} &= \frac{p_r}{p_\theta} x + \frac{r P^2}{p_\theta^3} p_x + f_{11} x_0^2 + f_{12} x_0 p_{x0} + f_{13} p_{x0}^2 + f_{14} z_0^2 + f_{15} z_0 p_{z0} + f_{16} p_{z0}^2, \\ \frac{dp_x}{d\theta} &= -\frac{p_r}{p_\theta} p_x - \left(B + r \frac{\partial B}{\partial r} \right) x + f_{21} x_0^2 + f_{22} x_0 p_{x0} + f_{23} p_{x0}^2 + f_{24} z_0^2 + f_{25} z_0 p_{z0} + f_{26} p_{z0}^2, \\ \frac{dz}{d\theta} &= \frac{r}{p_\theta} p_z + g_{11} x_0 z_0 + g_{12} x_0 p_{z0} + g_{13} p_{x0} z_0 + g_{14} p_{x0} p_{z0}, \\ \frac{dp_z}{d\theta} &= \left(r \frac{\partial B}{\partial r} - \frac{p_r}{p_\theta} \frac{\partial B}{\partial \theta} \right) z + g_{21} x_0 z_0 + g_{22} x_0 p_{z0} + g_{23} p_{x0} z_0 + g_{24} p_{x0} p_{z0}, \\ \frac{d\tau}{d\theta} &= \frac{\gamma r}{p_\theta} x + \frac{\gamma r p_r}{p_\theta^3} p_x + h_1 x_0^2 + h_2 x_0 p_{x0} + h_3 p_{x0}^2 + h_4 z_0^2 + h_5 z_0 p_{z0} + h_6 p_{z0}^2.\end{aligned}$$

Coefficient

Value.

f_{11}

$$\frac{P^2}{p_\theta^3} X_{11} X_{21} + \frac{3}{2} \frac{r p_r P^2}{p_\theta^5} X_{21},$$

f_{13}

$$\frac{P^2}{p_\theta^3} (X_{11} X_{22} + X_{12} X_{21}) + 2 \times \frac{3}{2} \frac{r p_r P^2}{p_\theta^5} X_{21} X_{22},$$

f_{14}

$$\frac{1}{2} \frac{r p_r}{p_\theta^3} Z_{21}^2,$$

f_{15}

$$\frac{r p_r}{p_\theta^3} Z_{21} Z_{22},$$

f_{16}

$$\frac{1}{2} \frac{r p_r}{p_\theta^3} Z_{22}^2,$$

f_{21}

$$\left(-\frac{\partial B}{\partial r} - \frac{r}{2} \frac{\partial^2 B}{\partial r^2} \right) X_{11}^2 - \frac{1}{2} \frac{P^2}{p_\theta^3} X_{21}^2,$$

f_{22}

$$\left(-2 \frac{\partial B}{\partial r} - r \frac{\partial^2 B}{\partial r^2} \right) X_{11} X_{12} - \frac{P^2}{p_\theta^3} X_{21} X_{22},$$

f_{23}

$$\left(-\frac{\partial B}{\partial r} - \frac{r}{2} \frac{\partial^2 B}{\partial r^2} \right) X_{12}^2 - \frac{1}{2} \frac{P^2}{p_\theta^3} X_{22}^2,$$

f_{24}

$$\frac{1}{2} r \left(\frac{\partial^2 B}{\partial r^2} + \frac{1}{r} \frac{\partial B}{\partial r} + \frac{1}{r^2} \frac{\partial^2 B}{\partial \theta^2} \right) Z_{11}^2 + \frac{\partial B}{\partial \theta} \frac{1}{p_\theta} Z_{11} Z_{21} - \frac{1}{2} \frac{1}{p_\theta} Z_{21}^2,$$

f_{25}

$$r \left(\frac{\partial^2 B}{\partial r^2} + \frac{1}{r} \frac{\partial B}{\partial r} + \frac{1}{r^2} \frac{\partial^2 B}{\partial \theta^2} \right) Z_{11} Z_{12} + \frac{\partial B}{\partial \theta} \frac{1}{p_\theta} (Z_{11} Z_{22} + Z_{12} Z_{21}) - \frac{1}{p_\theta} Z_{21} Z_{22},$$

f_{26}

$$\frac{1}{2} r \left(\frac{\partial^2 B}{\partial r^2} + \frac{1}{r} \frac{\partial B}{\partial r} + \frac{1}{r^2} \frac{\partial^2 B}{\partial \theta^2} \right) Z_{12}^2 + \frac{\partial B}{\partial \theta} \frac{1}{p_\theta} Z_{12} Z_{22} - \frac{1}{2} \frac{1}{p_\theta} Z_{22}^2,$$

g_{11}

$$\frac{1}{p_\theta} X_{11} Z_{21} + \frac{r p_r}{p_\theta^3} X_{21} Z_{21},$$

g_{12}

$$\frac{1}{p_\theta} X_{11} Z_{22} + \frac{r p_r}{p_\theta^3} X_{21} Z_{22},$$

g_{13}

$$\frac{1}{p_\theta} X_{12} Z_{21} + \frac{r p_r}{p_\theta^3} X_{22} Z_{21},$$

g_{14}

$$\frac{1}{p_\theta} X_{12} Z_{22} + \frac{r p_r}{p_\theta^3} X_{22} Z_{22},$$

g_{21}

$$\left(\frac{\partial B}{\partial r} + r \frac{\partial^2 B}{\partial r^2} - \frac{p_r}{p_\theta} \frac{\partial^2 B}{\partial r \partial \theta} \right) X_{11} Z_{11} - \frac{p_r^2}{p_\theta^3} \frac{\partial B}{\partial \theta} X_{21} Z_{11},$$

g_{22}

$$\left(\frac{\partial B}{\partial r} + r \frac{\partial^2 B}{\partial r^2} - \frac{p_r}{p_\theta} \frac{\partial^2 B}{\partial r \partial \theta} \right) X_{11} Z_{12} - \frac{p_r^2}{p_\theta^3} \frac{\partial B}{\partial \theta} X_{21} Z_{11},$$

g_{23}

$$\left(\frac{\partial B}{\partial r} + r \frac{\partial^2 B}{\partial r^2} - \frac{p_r}{p_\theta} \frac{\partial^2 B}{\partial r \partial \theta} \right) X_{12} Z_{11} - \frac{p_r^2}{p_\theta^3} \frac{\partial B}{\partial \theta} X_{22} Z_{11},$$

g_{24}

$$\left(\frac{\partial B}{\partial r} + r \frac{\partial^2 B}{\partial r^2} - \frac{p_r}{p_\theta} \frac{\partial^2 B}{\partial r \partial \theta} \right) X_{12} Z_{22} - \frac{p_r^2}{p_\theta^3} \frac{\partial B}{\partial \theta} X_{22} Z_{12},$$

h_1

$$\frac{\gamma p_r}{p_\theta^3} X_{11} X_{21} + \frac{1}{2} \left(\frac{\gamma r}{p_\theta^3} + \frac{3 \gamma r p_r^2}{p_\theta^5} \right) X_{21}^2,$$

h_2

$$\frac{\gamma p_r}{p_\theta^3} (X_{11} X_{22} + X_{12} X_{21}) + 2 \times \frac{1}{2} \left(\frac{\gamma r}{p_\theta^3} + \frac{3 \gamma r p_r^2}{p_\theta^5} \right) X_{21} X_{22},$$

h_3

$$\frac{\gamma p_r}{p_\theta^3} X_{12} X_{22} + \frac{1}{2} \left(\frac{\gamma r}{p_\theta^3} + \frac{3 \gamma r p_r^2}{p_\theta^5} \right) X_{22}^2,$$

h_4

$$\frac{1}{2} \frac{\gamma r}{p_\theta^3},$$

h_5

$$\frac{\gamma r}{p_\theta^3},$$

h_6

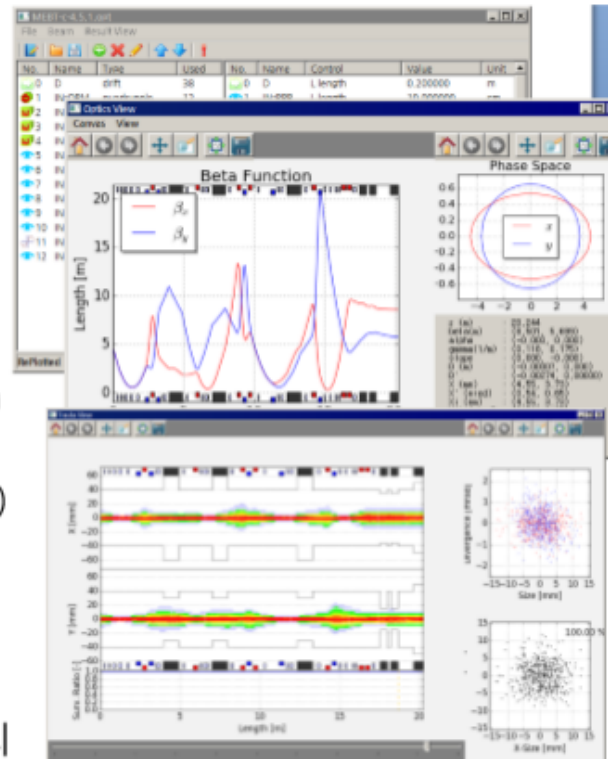
$$\frac{\gamma r}{p_\theta^3},$$

Beam dynamics program II

- ❖ PAL: Particle Accelerator Library by Garam Hahn.
- ❖ 2D/3D Vector analysis, 4D interpolation, RK4 tracker, etc.
- ❖ Apps: Beam line tracker, EQ orbit finder, FANA, G4KHIMA, etc.

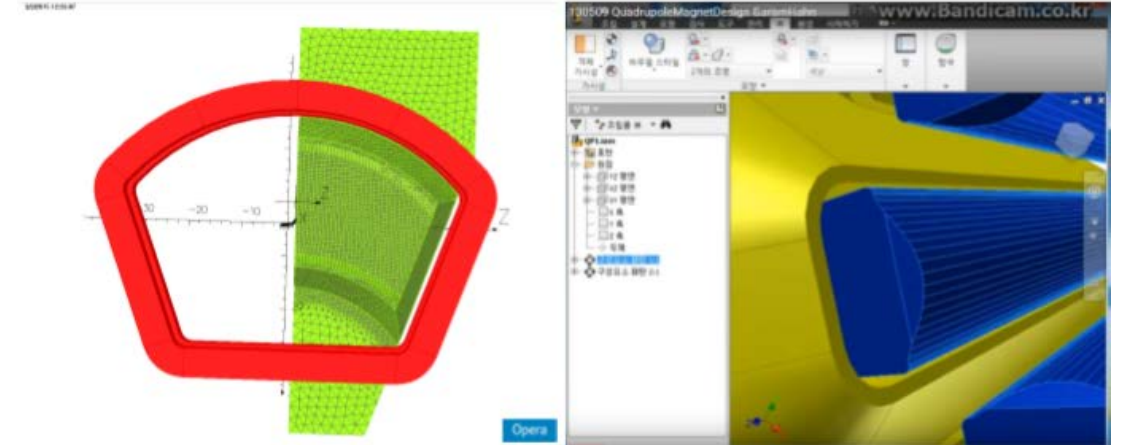
Optics Expert

- Linear Beam Optics Calc.
- Features
 - Graphic User Interface
 - Mouse drag tuning
 - Easy beam definition
 - Minimization algorithm
 - Real-time Calc. & visualization
 - Inverse tracing
 - Optical tracking (Tr. ratio Calc.)
 - Save As (MadX, TRACE3D, WinAgile)
 - Making a report (Latex, Excel) as automated manner
 - 제어와 연동 가능한 라이브러리



Magnet Builder

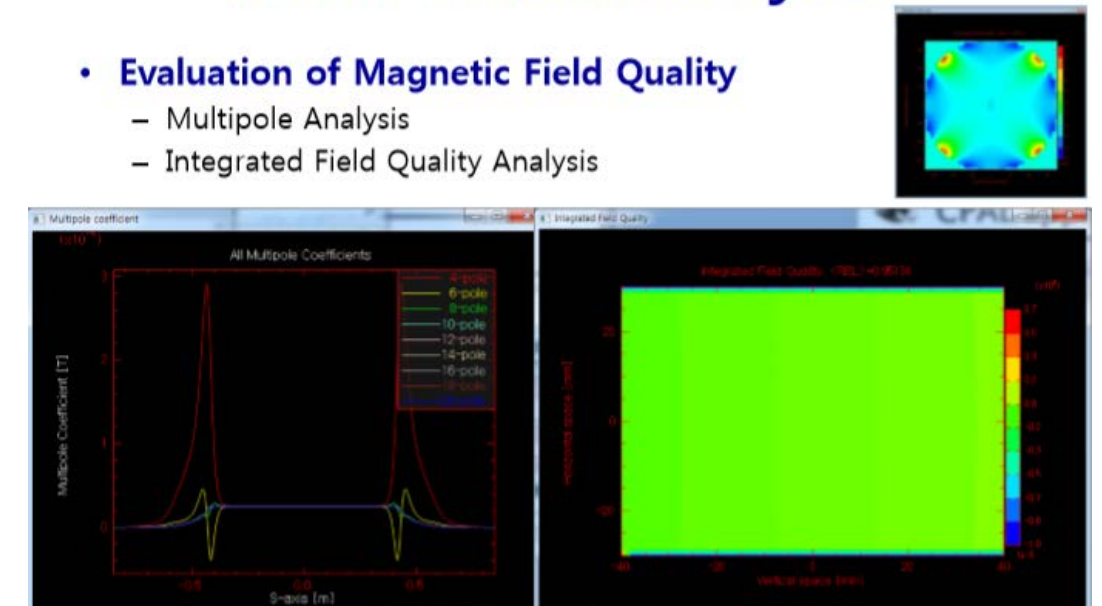
- Automatic File Generation
 - FEM Simulation : Opera3D COMI, Superfish POISSON
 - CAD Drawing : Autodesk Inventor, Free CAD v14



<https://www.youtube.com/watch?v=PPFh4vHQSgc>

FANA : Field Analyzer

- Evaluation of Magnetic Field Quality
 - Multipole Analysis
 - Integrated Field Quality Analysis



Preliminary design study

- ❖ Key Concepts: No Insulation (NI) / Multi-Width (MW) / Cryocooling
- ❖ Electromagnetic Design: Parameter Sweep for Main Yoke
- ❖ Electromagnetic Design: Hill Yoke Design toward isochronous field
- ❖ Mech. Analysis with Force Balance Equation: Peak Strain < 0.33 %
- ❖ Preliminary Quench Analysis: 168 K Rise, 4.3 MN Unbalanced Force

IEEE TRANSACTIONS ON APPLIED SUPERCONDUCTIVITY, VOL. 30, NO. 4, JUNE 2020

4400705

A Design Study on No-Insulation HTS Isochronous Cyclotron Magnet for Carbon Ion Therapy

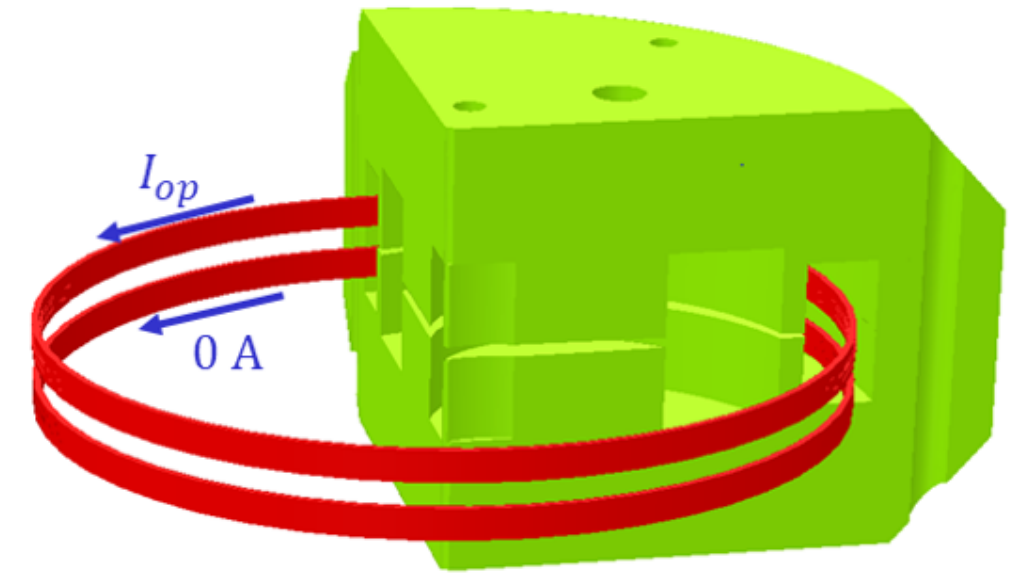
Jeonghwan Park, Garam Hahn, Jeseok Bang, Uijong Bong ^{ID}, Kibum Choi, Jung Tae Lee, and Seungyong Hahn

Abstract—Provided that a cyclotron system requires DC magnetic field, the no-insulation (NI) high temperature superconductor (HTS) magnet may be a good candidate as it may enable the cyclotron magnet to be more compact and reliable, yet operate under the liquid-helium-free environment. Here we report on a design study on an NI HTS isochronous cyclotron magnet for an acceleration of carbon ion up to an energy level of 385 MeV/u.

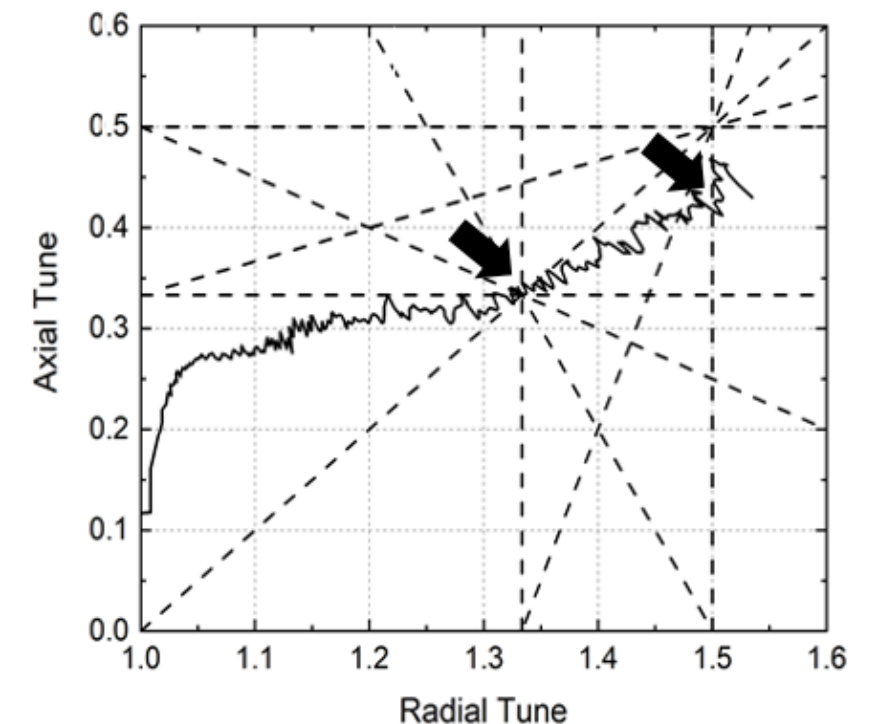
beam; and (3) simplicity to operate magnet by requiring of fixed DC magnetic field.

Encouraged by the recent progress of the no-insulation (NI) high temperature superconductor (HTS) magnet technology [9]–[16], multiple groups have proposed NI HTS magnets, as an alternative of its low temperature superconductor (LTS) coun-

Fig. Quarter model for magnetic simulation

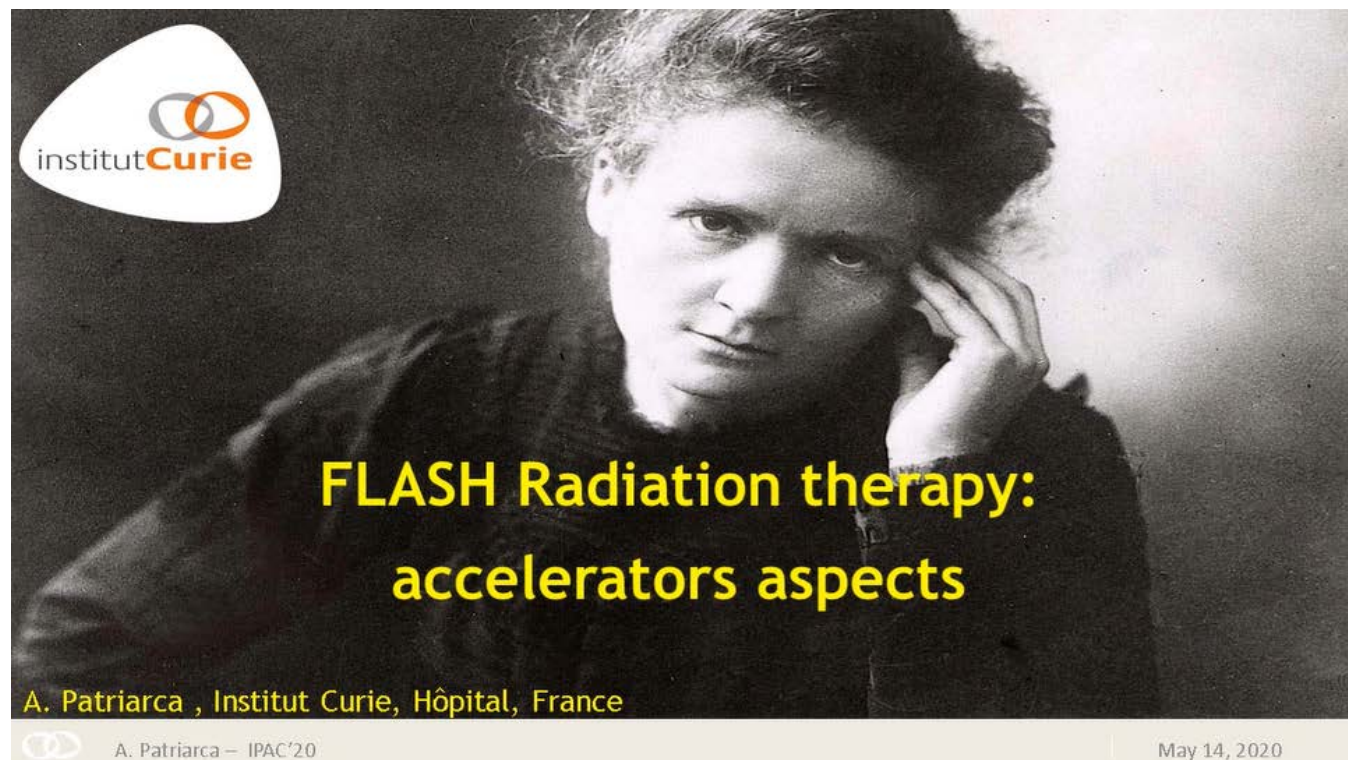


10 MeV to 4620 MeV with 10 MeV interval

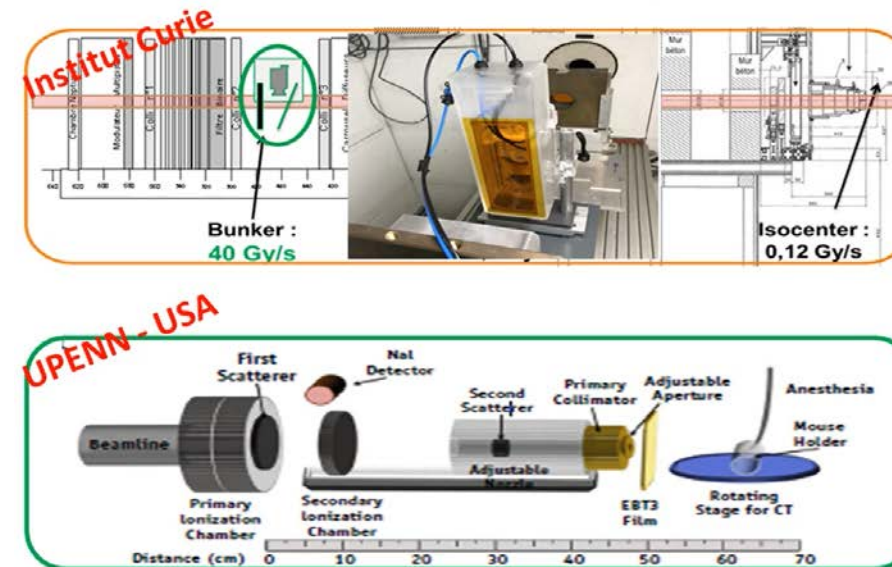


0.3 MW Cyclotron

- ❖ Good candidate on Flash therapy
- ❖ Also good candidate on high power injector
- ❖ First step: Proto-type low energy high current Cyclotron (10 MeV, 1 mA , proton)
- ❖ **Second step: 0.3 MW cyclotron for Flash therapy as well as injector for ADS**



Accelerators for pre-clinical FLASH investigations: protons

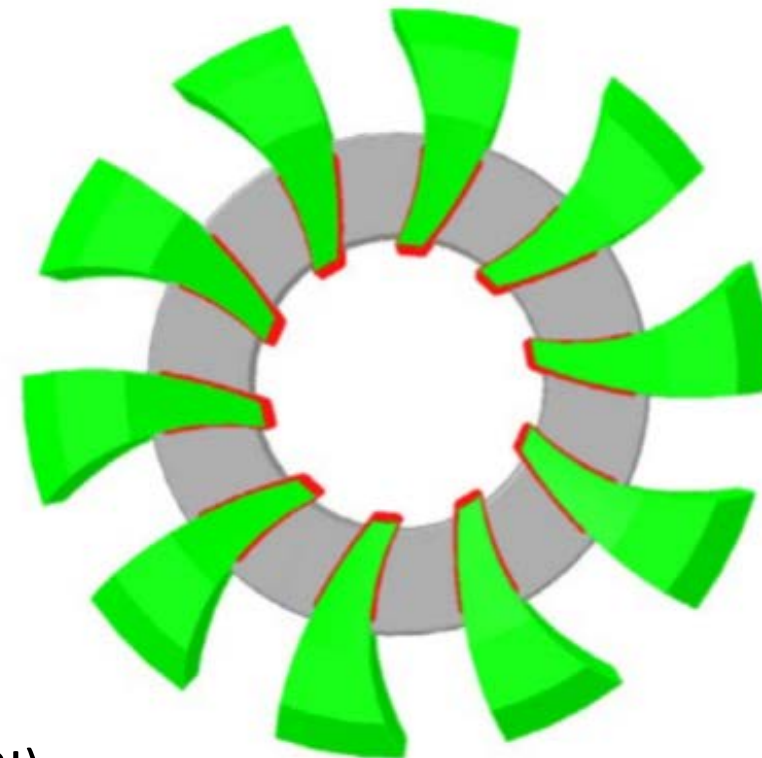
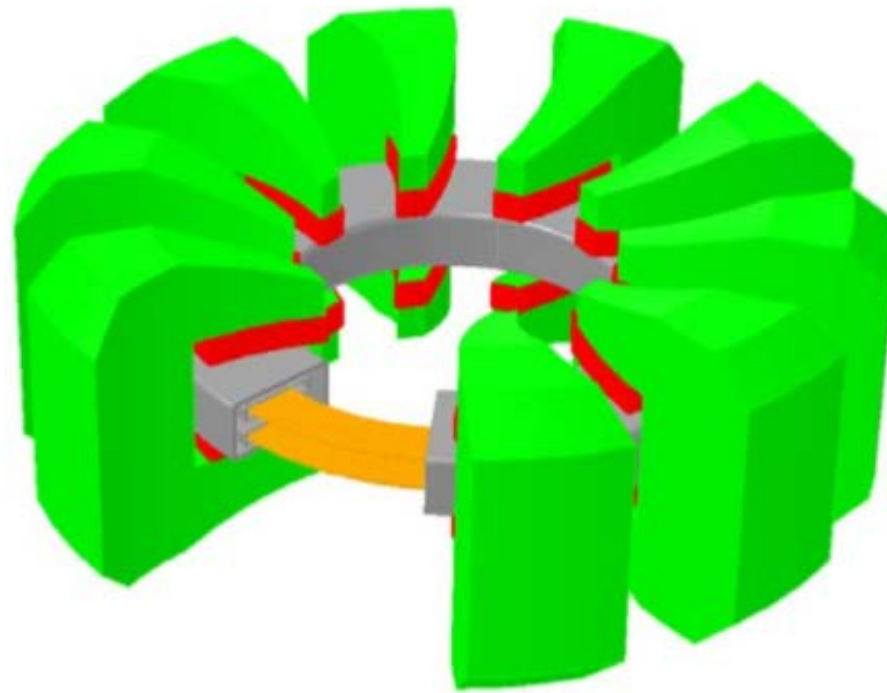


- Isochronous cyclotrons and passive beams
- Energy : 200 and 230 MeV
- Frequency : 106 MHz
- Beam current at cyclotron : 200 - 300 nA
- Dose rate at the sample level : 40 - 100 Gy/s
- Irradiation surface : $12 \times 12 \text{ mm}^2$

A. Patriarca, Institut Curie, IPAC20

3 MW Cyclotron

- ❖ **Third step: 3 MW main cyclotron for ADS**
- ❖ Multi layer separated-sector cyclotron by Dr. H. Kim and Prof. J. Chai (SKKU)
 - increasing the maximum beam current by two layers and double frequency RF system (four injector)
 - low cost but high power efficiency
 - 750 MeV Proton with 4 mA beam current



H. Kim (NFRI)

Thank you!

